Analysis of Markov chain algorithms on spanning trees, rooted forests, and connected subgraphs

Johannes Fehrenbach and Ludger Rüschendorf University of Freiburg

Abstract

In this paper we analyse a natural edge exchange Markov chain on the set of spanning trees of an undirected graph by the method of multicommodity flows. The analysis then is refined to obtain a canonical path analysis too. The construction of the flow and the canonical paths is based on related path constructions in a paper of Cordovil and Moreira (1993) on block matroids. The estimates of the congestion measure imply a polynomial bound on the mixing time. The canonical paths for spanning trees also yield polynomial time mixing rates for some related Markov chains on the set of forests with roots and on the set of connected spanning subgraphs. We obtain a parametric class of stationary distributions from which we can efficiently sample. For rooted forests this includes the uniform distribution. For connected spanning subgraphs the uniform distribution is not covered.

Keywords: spanning trees, randomized algorithm, multicommodity flow, canonical paths, Markov chain, rooted forests, connected subgraphs

1 Introduction

Counting the number of spanning trees in an undirected, connected, loop-free graph is one of the few counting problems on graphs G = (V, E) which can be solved deterministically in polynomial time. Remind that a spanning tree is a maximum cardinality cycle free subgraph (V, S) of G. If $D = \text{diag}(d_0, \ldots, d_{n-1})$ is the diagonal matrix with the degrees d_0, \ldots, d_{n-1} of the *n* vertices in *V* on its main diagonal and if *A* denotes the adjacency matrix of *V*, then the classical Kirchhoff-formula states that for all $0 \le i \le n-1$:

spanning trees of $G = \det(D - A)_{ii}$ (1.1)

where $(D-A)_{ii}$ is the $(n-1) \times (n-1)$ principal submatrix of D-A obtained by deleting the *i*th row and the *i*th column. Since the determinant of a matrix may be computed in time $O(n^3)$ by the Gaussian elimination algorithm this formula implies a polynomial time algorithm for counting spanning trees in an undirected graph. Various techniques have been developed to establish randomized approximation schemes (RAS) in particular for the approximative counting of combinatorial and graph-theoretic structures. For a survey see Jerrum and Sinclair (1996) or Jerrum (2003). These *Markov chain Monte Carlo methods* have been successfully applied to establish approximative polynomial time counting algorithms for a series of difficult counting and approximation problems like the number of perfect matchings, the graph colouring problem, the approximation of the partition function in the Ising model, the volume of convex bodies, and many others.

The basic problem is as follows. Let $\Omega = \Omega_n$ be a finite set depending on the length *n* of the *input* (like the number of nodes *n* in a graph-theoretic problem). Let $N = N_n$ be the (unknown) number of elements of Ω . Then a random algorithm $A = A_n$ is called a fully polynomial randomized approximation scheme (FPRAS) of N if for all n and for all small $\varepsilon, \delta \in (0, 1)$

$$P\left((1-\varepsilon)N \le A \le (1+\varepsilon)N\right) \ge 1-\delta \tag{1.2}$$

where the algorithm runs in time bounded by a polynomial in n, ε^{-1} and δ^{-1} . Note that $N = N(n, \varepsilon, \delta)$, $A = A(n, \varepsilon, \delta)$ depend on n, ε, δ and typically N grows exponentially fast in n. Therefore, a naive Monte-Carlo algorithm will not work in this case. The dependence on δ can be easily neglected by repeated sampling.

Jerrum, Valiant, and Vazirani (1986) suggested a RAS by reducing the problem of approximative counting of $N = |\Omega|$ to that of almost uniform random sampling in the following way:

Assume that there is some decreasing sequence of subsets $\Omega = \Omega_0 \supset \Omega_1 \supset \cdots \supset \Omega_r$ with the following properties:

(1.3)

- a) $|\Omega_r|$ can be calculated
- b) $|\Omega_i| / |\Omega_{i+1}|$ is polynomial bounded in *n* for $0 \le i < r$
- c) $r = r_n$ is polynomially bounded in n
- d) For $0 \le i < r$ elements of Ω_i can be sampled approximatively uniformly in polynomial time with respect to n.

Then by iterative sampling in Ω_i as in d) one obtains an estimator \bar{X}_i of $|\Omega_{i+1}|/|\Omega_i|$ for $0 \le i < r$. By b) a polynomial number of samples in n and ε^{-1} is sufficient. Define the RAS A by

$$A := |\Omega_r| |\bar{X}|^{-1} \tag{1.4}$$

where $\bar{X} := \prod_{i=0}^{r-1} \bar{X}_i$. By a) and c) \bar{X} can be calculated in polynomial time. Typically it will be not difficult to construct natural subsequences Ω_i such that a), b), c) hold. In typical applications the Ω_i are of the same structure as Ω (with different size). So solving d) for $\Omega_0 = \Omega$ yields solutions of d) for any Ω_i . This property is called *self-reducibility* in Jerrum et al. (1986). But the challenge is condition d) for $\Omega = \Omega_0$ The main tool for constructing approximatively uniform samples is to construct a suitable Markov chain \mathfrak{M} which has as its stationary distribution the uniform distribution on Ω . (A well-known application of this method is the simulated annealing algorithm.)

The main technical problem is to establish that the used Markov chain is rapidly mixing. This property then yields that sampling can be done efficiently (in polynomial time). Several tools have been developed to this aim. The main tools are various eigenvalue estimates for the second largest eigenvalue of the transition matrix (Diaconis and Stroock (1991)), coupling methods (see e.g., Aldous (1983) or Diaconis (1988)) the conductance method and the method of canonical paths (see Diaconis and Stroock (1991) and Sinclair (1993)). Here the basic idea to obtain a good upper bound on the mixing time of the Markov chain is to select a set $\Gamma = \{\gamma_{xy}; x, y \in \Omega\}$ of *canonical paths* γ_{xy} for each pair (x, y) such that no transition e = (v, w) of the graph of the chain is too often used in the corresponding flow problem. Define the congestion measure $\varrho = \varrho(\Gamma)$ by

$$\varrho(\Gamma) = \max_{e=(v,w)\in E} \frac{1}{\pi(v)P(v,w)} \sum_{(x,y):\gamma_{xy}\ni e} \pi(x)\pi(y)|\gamma_{xy}|.$$
(1.5)

Here P(v, w) is the transition matrix of the Markov chain, π is the stationary distribution and $|\gamma_{xy}|$ is the length of the path γ_{xy} . The sum term is the total flow through edge e while the first term is the inverse capacity of edge e. By a result of Diaconis and Stroock (1991) one obtains for irreducible, aperiodic, reversible Markov chains with $P(x, x) \geq \frac{1}{2}$ for all $x \in \Omega$ the following estimate of the mixing time $\tau = \tau(\varepsilon)$:

$$\tau(\varepsilon) \le \varrho(\Gamma)(\log \widehat{\pi}^{-1} + \log \varepsilon^{-1}) \tag{1.6}$$

with $\widehat{\pi} = \min_{x \in \Omega} \pi(x)$. So the problem to bound the mixing time of the Markov chain can be reduced to obtain bounds on the congestion measure. Note that for the uniform distribution π the term $\log \widehat{\pi}^{-1}$ is polynomial in n, when as typically $N = |\Omega|$ is exponential in n.

To obtain bounds on $\rho(\Gamma)$ an important technique is *coding* of the transitions of the canonical path. For $e \in T = \{(x, y) \in \Omega \times \Omega : P(x, y) > 0\}$ define $\mathcal{P}_c(e) = \{(x, y) \in \Omega \times \Omega : \gamma_{xy} \ni e\}$, the set of pairs whose canonical path uses edge e. Then a *coding* is a system (η_e) of injective mappings $\eta_e : \mathcal{P}_c(e) \to \Omega, e \in T$. If π is the uniform distribution on Ω and (η_e) a coding, then we obtain the estimate

$$\varrho(\Gamma) = \max_{e=(v,w)\in T} \frac{1}{\pi(v)P(v,w)} \sum_{(x,y)\in\mathcal{P}(e)} \pi(x)\pi(y)|\gamma_{xy}|$$

$$\leq \max_{e=(v,w)\in T} \frac{\ell_{\max}}{P(v,w)} \sum_{(x,y)\in\mathcal{P}(e)} \pi(\eta_e(x,y))$$

$$\leq \max_{e=(v,w)\in T} \frac{\ell_{\max}}{P(v,w)}$$
(1.7)

where ℓ_{\max} denotes the maximal length of the canonical paths. If π is not the uniform distribution then a similar estimate holds if the coding is constructed such that

$$\pi(v)P(v,w)\pi(\eta_e(x,y)) \approx \pi(x)\pi(y).$$
(1.8)

The multicommodity flow technique is a natural extension of canonical paths introduced in Sinclair (1992). Let \mathcal{P}_{xy} denote the set of all directed paths from x to y in the Markov chain on Ω . Let $f_{xy} : \mathcal{P}_{xy} \to \mathbb{R}_0^+$ for $x, y \in \Omega$ be a set of functions such that $\sum_{p \in \mathcal{P}_{xy}} f_{xy}(p) = 1$. Then each f_{xy} is called a 1-flow from x to y. In particular any canonical path defines a 1-flow. Then the set $F = \{f_{xy}; x, y \in \Omega\}$ is called a *multicommodity flow*. Sinclair (1992) proved that the estimate of the mixing time in (1.7) extends to multicommodity flows F,

$$\tau(\varepsilon) \le \varrho(F)(\log \hat{\pi}^{-1} + \log \varepsilon^{-1})$$
(1.9)

where

$$\varrho(F) = \max_{e=(v,w)\in T} \frac{1}{\pi(v)P(v,w)} \sum_{p_{xy}\ni e} \pi(x)\pi(y)f_{xy}(p_{xy})|p_{xy}|$$
(1.10)

is the congestion measure of the flow F. To bound $\rho(F)$ we define for a transition $e \in T$ of \mathfrak{M} the set $\mathcal{P}(e) := \bigcup_{x,y \in \Omega} \{p \in \mathcal{P}_{xy} : e \in p \text{ and } f_{xy}(p) > 0\}$. A coding (η_e) , for a multicommodity flow F is a system of (not necessarily injective) mappings $\eta_e : \mathcal{P}(e) \to \Omega$ such that for all $z \in \Omega$

$$\sum_{\substack{p_{xy} \in \mathcal{P}(e):\\ \eta_e(p_{xy})=z}} f_{xy}(p_{xy}) \le 1.$$

$$(1.11)$$

Multicommodity flows are in some cases easier to construct than canonical paths. In some recent papers these were instrumental for constructing improved bounds for several basic counting problems (see Sinclair (1992)) and to obtain randomized approximation schemes for long time open problems as for the knapsack problem (Morris and Sinclair (2004)) and for the counting of contingency tables (Cryan, Dyer, Goldberg, and Jerrum (2002)).

In this paper we construct and analyse at first a multicommodity flow for the spanning tree problem and then refine the analysis to canonical paths which needs some technically involved considerations. In section two we introduce the natural Markov chain for this problem. The mixing time τ_s of this chain had been bounded from above using coupling arguments by Broder (1989) and Aldous (1990) who obtained a bound for the mixing time of the order

$$\tau_s(\varepsilon) = O(m^2 n^4 (n \log m + \log \varepsilon^{-1})) \tag{1.12}$$

with n = |V|, m = |E|. Feder and Mihail (1992) improved this bound using the conductance method to the order

$$\tau_s(\varepsilon) = O(mn^2(n\log m + \log \varepsilon^{-1})). \tag{1.13}$$

In fact they considered an extension of the problem to matroids which satisfy a certain balance-condition. Since for a graph G = (V, E) the pair $M = (E, \operatorname{ST}(G)) - \operatorname{ST}(G)$ the set of spanning trees of G – is a graphical matroid satisfying this balance condition, the spanning tree problem is included in their result. In a recent paper Jerrum and Son (2002)found a bound for the log Sobolev constant which leads to an improvement of the Feder and Mihail mixing result of the bases exchange walk for balanced matroids to the order $O(nm \log n)$.

Jerrum (1998) suggested that the construction of Cordovil and Moreira (1993) for paths in graphic block matroids is 'ideally suited to this purpose' but no further analysis is given in that paper. We prove in detail that based on the paths of Cordovil and Moreira (1993) a multicommodity flow and canonical paths can be defined such that no transition of the Markov chain carries too much weight. This is not at all obvious but needs some careful consideration of the canonical paths (see the proofs of Lemma 3.1 and of Theorem 3.2). As a result we establish that by the method of multicommodity flow one obtains the same bound for the mixing time obtained by Feder and Mihail (1992) by the conductance method but one does not reach the improved bound of Jerrum and Son (2002).

In the final sections we show that the canonical paths for spanning trees are also useful for the analysis of some related Markov chains on the set of forests with roots and on the set of connected spanning subgraphs. In both cases the Markov chains can be shown to be rapidly mixing. Their stationary distribution however is some distribution with weights given by the number of components (for the forest problem) and by the number of spanning trees (for the connected spanning subgraphs problem). For connected subgraphs the interesting case of the uniform distribution remains open.

2 Markov chain on spanning trees

In this section we introduce a Markov chain on the set ST(G) of spanning trees of an undirected graph G = (V, E) whose stationary distribution is the uniform distribution on ST(G). We also introduce some notions from graph theory and on matroids which are used for the construction of multicommodity flows in section 3.

The Markov chain $\mathfrak{M}_s(G) = (X_t)_{t \in \mathbb{N}}$ on $\mathrm{ST}(G)$ is defined by the transition probabilities. If $X_t = X \in \mathrm{ST}(G)$ is the state of $\mathfrak{M}_s(G)$ at time $t \in \mathbb{N}$, then we draw uniformly and independent $e \in X$ and $f \in E$ and set

1)
$$Y = (X \setminus \{e\}) \cup \{f\}$$

2) If $Y \in ST(G)$ then we set

$$X_{t+1} = \begin{cases} Y \\ X \end{cases} \quad \text{each with probability } \frac{1}{2}. \tag{2.1}$$

If $Y \notin ST(G)$, then we set $X_{t+1} = X$. We denote the transition matrix of $\mathfrak{M}_s(G)$ by P_s .

So the transitions of this chain are given by simple random exchanges of two edges as long as they lead again to spanning trees.

Proposition 2.1 The Markov chain $\mathfrak{M}_s(G)$ is ergodic and the stationary distribution of $\mathfrak{M}_s(G)$ is the uniform distribution on ST(G).

Proof: Ergodicity is equivalent to irreducibility and aperiodicity. The aperiodicity is obvious from construction and also for any $X \in ST(G)$ holds $P_s(X,X) > \frac{1}{2}$. For any $X, Y \in ST(G)$ we prove by induction on $k = |X \oplus Y|$, the cardinality of the symmetric difference of X and Y, that $P_s^t(X,Y) > 0$ for some $t \in \mathbb{N}$. Note that $k = |X \oplus Y| \in 2\mathbb{N}$. If $k = 2, X \oplus Y = \{a, b\}, a \in X, b \in Y$. Then choosing (with positive probability) e = a and f = b in the definition of the chain one gets $X_{t+1} = Y$ and $P_s(X,Y) > 0$. If k > 2 and $b \in Y \setminus X$ then $X \cup \{b\}$ contains a circle C with some edge a in C such that $a \in X \setminus Y$. Choosing (with positive probability) e = a, f = b, then $X' = (X \setminus \{a\}) \cup \{b\} \in ST(G)$ and $P_s(X, X') > 0$. Furthermore, $|X' \oplus Y| = k - 2$ and so by the induction hypothesis $P_s^t(X', Y) > 0$ for some $t \in \mathbb{N}$ and thus $P_s^{t+1}(X, Y) > 0$.

For any $X, Y \in \operatorname{ST}(G)$ with $P_s(X, Y) > 0$, $X \neq Y$ holds $P_s(X, Y) = \frac{1}{2(n-1)m} = P_s(Y, X)$ where n = |V|, m = |E|, i.e. the transition matrix is symmetric and thus reversible w.r.t. the uniform distribution π on $\operatorname{ST}(G)$. This implies that the uniform distribution π is the stationary distribution of $\mathfrak{M}_s(G)$.

The construction of the multicommodity flow in section three uses for its proof an idea of Cordovil and Moreira (1993) for graphical block-matroids. For the ease of reference we remind that a matroid M = (S, B) is a pair of nonempty sets, $B \subset \mathfrak{P}(S)$, such that for all $X, Y \in B$ holds: $\forall x \in X \setminus Y$ exists some $y \in Y \setminus X$ such that $(X \setminus \{x\}) \cup \{y\} \in B$. Elements of B are called bases of M. A matroid M = (S, B) is called block-matroid if $S = X \cup Y$ for some $X, Y \in B$.

In our context we consider the graphical matroid (E, ST(G)) which is a graphical block-matroid if G can be decomposed into two disjoint spanning trees, see Figure 1.



Figure 1: A graphical block-matroid on the left with a decomposition into two spanning trees.

For a block-matroid M = (S, B) a basis element $X \in B$ is a *basis-cobasis* of M if $S \setminus X \in B$. The basis-cobasis graph H = (V', E') is defined by $V' = \{X \in B; X \text{ is basis-cobasis of } M\}, E' = \{\{X_1, X_2\} \subset B; |X_1 \oplus X_2| = 2\}.$

Cordovil and Moreira (1993) proved constructively the following result:

Theorem 2.2 Let M be a graphical block-matroid with basis-cobasis graph H = (V', E'). Then for any $X, Y \in V'$ there exists a connecting path from X to Y in H of length $\frac{1}{2}|X \oplus Y|$.

We will use the contraction of graphs along edges e in order to reduce our spanning tree problem to the framework of block-matroids and the basis-cobasis graph. To explain the contraction G/e on an edge e see the following example.



Figure 2: Contraction of a graph on edge *e*.

Here the graph is contracted on edge e with end nodes v, w, These contracted nodes give rise to a new node v_e , while edge e disappeared. For a formal definition see Diestel (1996). For any subset $S \subset E$ let G/S denote the contraction on all edges in S.

3 Bounding the mixing time of \mathfrak{M}_s

We show now how to bound the mixing time of $\mathfrak{M}_s(G)$ via the multicommodity flow technique described in section 1.

Construction of the multicommodity flow F_{G} :

For a graph G = (V, E), we have to define for each pair $X, Y \in ST(G)$ a 1-flow $f_{XY} : \mathcal{P}_{XY} \to \mathbb{R}_0^+$ with

$$\sum_{p \in \mathcal{P}_{XY}} f_{XY}(p) = 1.$$
(3.1)

To do this, we set $M := (V, X \cup Y)/(X \cap Y)$ as the graph with the nodes of G and the edges of $X \cup Y$ contracted on the edges of $X \cap Y$. While the nodes of M correspond to the connected components of $(V, X \cap Y)$, the edges of M are those of the symmetric difference $X \oplus Y := (X \cup Y) \setminus (X \cap Y)$.

Now $X \setminus Y$ and $Y \setminus X$ are two disjoint spanning trees of M and thus M forms a graphic block-matroid. Each spanning tree of M can be enhanced

to an element of $\operatorname{ST}(G)$ by adding the edges of $X \cap Y$. So the basis-cobasis graph of M corresponds to a subgraph of the transition graph of $\mathfrak{M}_s(G)$. A path $p' = (B'_i)_{0 \leq i \leq \ell}$ in this basis-cobasis graph can be transferred to a path $p = (B_i)_{0 \leq i \leq \ell}$ in \mathfrak{M}_s by setting $B_i := B'_i \cup (X \cap Y)$ for all $0 \leq i \leq \ell$. Exactly to these paths f_{XY} will assign a positive weight. The construction due to Cordovil and Moreira (1993) is inductive over the number |M| of nodes in M. We next show that this construction can be used to establish inductively a multicommodity flow on $\operatorname{ST}(G)$.

If |M| = 1, then X = Y and nothing is to do. In the case |M| = 2, X and Y are neighbours in $\mathfrak{M}_s(G)$. We define $f_{XY}(p) = 1$ for the path $p = (B_i)_{0 \le i \le 1}$ which consists only of the transition from X to Y, i.e. $B_0 := X$ and $B_1 := Y$. For all other $p' \in \mathcal{P}_{XY} \setminus \{p\}$ we set $f_{XY}(p') := 0$, so equation (3.1) holds. Generally we encode a transition (B_i, B_{i+1}) in a path $(B_i)_{0 \le i \le \ell}$ that carries any weight in F_G by $\overline{B}_i := B_0 \oplus B_\ell \oplus B_i$. We have also to take care that this encoding is a spanning tree. For the above path p from X to Y we get $\overline{B}_0 = X \oplus Y \oplus X = Y$, which is clearly an element of ST(G).

For $|M| = \ell + 1$ let d_{\min} be the minimal degree of a node in M and Dthe set of nodes of degree d_{\min} . Then $d_{\min} = 2$ or $d_{\min} = 3$ because X and Yare spanning trees. Next for each $v \in D$ we select a pair $X_v, Y_v \in ST(G)$ that satisfies the induction hypothesis, and thus $f_{X_vY_v}$ is already defined. Further for each path $p' \in \mathcal{P}_{X_vY_v}$ with $f_{X_vY_v}(p') > 0$ we construct an extension $p \in \mathcal{P}_{XY}$ and we say p is based on p'. Let

$$\mathcal{V}(p) := \bigcup_{v \in D} \{ p' \in \mathcal{P}_{_{X_vY_v}} \mid p \text{ is based on } p' \}$$

be the set of all paths p is based on. Then we define

$$f_{XY}(p) := \sum_{p' \in \mathcal{V}(p)} \frac{1}{|D|} f_{X'Y'}(p'),$$

where X' and Y' are start and end nodes of p' respectiveley. As for all $X, Y \in ST(G)$

$$\bigcup_{p\in\mathcal{P}_{XY}}\mathcal{V}(p)=\bigcup_{v\in D}\{p'\in\mathcal{P}_{X'Y'}\mid f_{X'Y'}(p')>0\},$$

the induction hypothesis gives

$$\sum_{p \in \mathcal{P}_{XY}} f_{XY}(p) = \sum_{p \in \mathcal{P}_{XY}} \sum_{p' \in \mathcal{V}(p)} \frac{1}{|D|} \cdot f_{X'Y'}(p')$$
$$= \frac{1}{|D|} \cdot \sum_{v \in D} \sum_{p' \in \mathcal{P}_{X_vY_v}} f_{X_vY_v}(p')$$
$$= \frac{1}{|D|} \cdot \sum_{v \in D} 1$$
$$= 1.$$

So f_{XY} satisfies equation (3.1). We show now how to select for $v \in D$ the pair X_v, Y_v and how to derive from the paths in $\mathcal{P}_{X_vY_v}$ the paths of \mathcal{P}_{XY} .

If $d_{\min} = 2$ let $a \in X$ and $b \in Y$ be the two edges in M at this node v and set $X_v := (X \setminus \{a\}) \cup \{b\}$ and $Y_v := Y$. For this pair the induction hypothesis holds because $M_v := (V, X_v \cup Y_v)/(X_v \cap Y_v) = (M/b) \setminus \{a\}$ has exactly ℓ nodes. A path $p' = (B'_i)_{0 \leq i < \ell} \in \mathcal{P}_{X_v Y_v}$ can easily be transformed into a path $p = (B_i)_{0 \leq i \leq \ell} \in \mathcal{P}_{XY}$ by adding the transition from X to X_v at the first step. Formally $B_0 := X$ and $B_{i+1} := B'_i$ for all $0 \leq i < \ell$.

The encodings $(\bar{B}_i)_{0 \leq i < \ell}$ of p can also be derived from the encodings $(\bar{B}'_i)_{0 \leq i < \ell-1}$ of p': We encode the transition (B_i, B_{i+1}) by $\bar{B}_i := X \oplus Y \oplus B_i = (\bar{B}'_{i+1} \setminus \{b\}) \cup$ $\{a\}$ for $1 \leq i < \ell$ and $\bar{B}_0 := Y$. These are all spanning trees because in \bar{B}'_{i-1} the edge b is the only one at node v.

Now let $d_{\min} = 3$ and w.l.o.g. let $a, b \in X$ and $c \in Y$ be the edges at v in M. Further let a be that edge that is included in the only circle in $X \cup \{c\}$. We define $X_v := X$ and $Y_v := (Y \setminus \{c\}) \cup \{a\}$ and so the induction hypothesis holds for the pair X_v, Y_v because the graph $M_v := (V, X_v \cup Y_v)/(X_v \cap Y_v) = (M/a) \setminus \{c\}$ contains ℓ nodes.

To derive $p = (B_i)_{0 \le i \le \ell} \in \mathcal{P}_{XY}$ out of a path $p' = (B'_i)_{0 \le i < \ell} \in \mathcal{P}_{X_vY_v}$ we look at that transition in p' which exchanges the edge b, e.g., $b \in B'_j \oplus B'_{j+1}$ for some $j \in \{0, \ldots, \ell-2\}$. We then define:

$$B_i := \begin{cases} B'_i, & i < j \\ (B'_{i-1} \setminus \{a\}) \cup \{c\}, & i > j \end{cases}$$

for all $i \in \{0, \ldots, \ell\} \setminus \{j\}$ and

$$B_j := \begin{cases} (B'_{j-1} \setminus \{a\}) \cup \{c\}, \text{ if spanning tree} \\ (B'_{j-1} \setminus \{b\}) \cup \{c\}, \text{ otherwise.} \end{cases}$$
(3.3)

$$p': \underbrace{X \longrightarrow \dots \longrightarrow B'_{j-1}}_{\downarrow} \xrightarrow{-b+d} \underbrace{B'_j \longrightarrow \dots \longrightarrow Y_v}_{\downarrow -a+c}$$

$$p: \underbrace{X \longrightarrow \dots \longrightarrow B_{j-1}}_{-b+c} \xrightarrow{-a+c} B_j \xrightarrow{-b+d}_{-a+d} \underbrace{B_{j+1} \longrightarrow \dots \longrightarrow Y}_{J-a+c}$$

The $(B_i)_{0 \le i < j}$ are spanning trees because of the hypothesis. For i > j the edge a is the only edge at v in B'_{i-1} and, therefore, the exchange of a by c leads to another spanning tree B_i . Finally in (3.3) that edge is removed which is contained in the circle in $B'_{i-1} \cup \{c\}$. This guarantees $B_j \in ST(G)$. At last we

have to make sure that the encodings $\overline{B}_i = X \oplus Y \oplus B_i$ are also spanning trees. By definition is

$$\bar{B}_i = \begin{cases} (\bar{B}'_i \setminus \{a\}) \cup \{c\}, \ i < j \\ \bar{B}'_{i-1}, & i > j \end{cases}$$

for all $i \in \{0, \ldots, \ell - 1\} \setminus \{j\}$. It follows as before, that these are all spanning trees. $\bar{B}_j = X \oplus Y \oplus B_j$ needs a little more work. In the first case in (3.3) holds

$$\bar{B}_j = X \oplus ((Y_v \setminus \{c\}) \cup \{a\}) \oplus ((B'_{j-1} \setminus \{c\}) \cup \{a\})$$

= $X \oplus Y_v \oplus B'_{j-1}$
= \bar{B}'_{j-1}

Obviously this is a spanning tree by the hypothesis. In the second case in (3.3) we have

$$\bar{B}_j = X \oplus ((Y_v \setminus \{c\}) \cup \{a\}) \oplus ((B'_{j-1} \setminus \{c\}) \cup \{b\})$$

= $X \oplus Y_v \oplus B'_{j-1} \oplus \{a, b\}$
= $(\bar{B}'_{j-1} \setminus \{a\}) \cup \{b\}.$

The circle in $\bar{B}'_{j-1} \cup \{b\}$ must include a and that is why \bar{B}_j also in this case is a spanning tree.

The multicommodity flow $F_G := \{f_{XY} \mid X, Y \in \mathrm{ST}(G)\}$ on $\mathfrak{M}_s(G)$ and its codings are now defined. Because the functions $f_{XY} : \mathcal{P}_{XY} \to \mathbb{R}_0^+$ are defined on disjoint sets we can look at F_G as a function on $\mathcal{P} := \bigcup_{X,Y \in \mathrm{ST}(G)} \mathcal{P}_{XY}$ to \mathbb{R}_0^+ and we write

$$F_G(p) = f_{XY}(p)$$
 for all $p \in \mathcal{P}_{XY}$ and all $X, Y \in ST(G)$.

The inductive construction of F_G has the positive effect that a 1-flow $f_{XY} \in F_G$ does not differ much to another flow $f_{X'Y'} \in F_G$ if the spanning trees X, X' and Y, Y' are very similar. The following lemma makes this clear.

Lemma 3.1 Given $X, Y \in ST(G)$ and a node w in $M := (V, X \cup Y)/(X \cap Y)$ of degree 3. The three edges in M at w are $a, b \in Y$ and $c \in X$. Then $X^a := (X \setminus \{c\}) \cup \{a\}$ and $X^b := (X \setminus \{c\}) \cup \{b\}$ are also spanning trees. Furthermore, let $p_a = (A_i)_{0 \le i \le \ell} \in \mathcal{P}_{X^{a_Y}}$ and $p_b = (B_i)_{0 \le i \le \ell} \in \mathcal{P}_{X^{b_Y}}$ be the paths with

$$A_i = \begin{cases} B_i \oplus \{a, b\}, \ 0 \le i \le j \\ B_i, \qquad j < i \le \ell \end{cases}$$

$$(3.4)$$

where j is that step in p_a which exchanges b, i.e. $b \in A_j \oplus A_{j+1}$. Then for these paths p_a, p_b and the multicommodity flow F_G holds

Similary, for $p'_a \in (A'_i)_{0 \le i \le \ell} \in \mathcal{P}_{_{YX^a}}$ and $p'_b = (B'_i)_{0 \le i \le \ell} \in \mathcal{P}_{_{YX^b}}$ with

$$A'_{i} = \begin{cases} B'_{i}, & 0 \le i \le j\\ B'_{i} \oplus \{a, b\}, & j < i \le \ell \end{cases}$$

where again $j \in \{0, \ldots, \ell - 1\}$ with $b \in A'_j \oplus A'_{j+1}$ holds $F_G(p'_a) = F_G(p'_b)$.

Proof: By definition of X^a and X^b , one can easily see that the graphs $M^a := (V, X^a \cup Y)/(X^a \cap Y)$ and $M^b := (V, X^b \cup Y)/(X^b \cap Y)$ are isomorph. If a connects the nodes w and t and b the nodes w and s in M, then $I : M^a \to M^b$ given by

$$I(v) := \begin{cases} v, \ v \notin \{v_a, s\} \\ t, \ v = v_a \\ v_b, \ v = s \end{cases} \quad \text{und} \quad I(e) := \begin{cases} e, \ e \neq b \\ a, \ e = b \end{cases}$$

for all nodes v and edges e in M^a defines an isomorphism. Figure ?? shows an example.



Figure 3: An example for a graph M from Lemma 3.1. The resulting graphs M^a and M^b are isomorph.

The number of nodes in M^a is the same as that in M^b . The proof of Lemma 3.1 is given by induction over $|M^a|$:

For $|M^a| = 2$ the path $p_a = (A_i)_{0 \le i \le 1}$ given by $A_0 = X^a$ and $A_1 = Y$ is the only path in $\mathcal{P}_{X^{a_Y}}$ with a positive weight in F_G , i.e. $F_G(p_a) = 1$. The same holds for $p_b = (B_i)_{0 \le i \le 1}$ given by $B_0 = X^b = (A_0 \setminus \{a\}) \cup \{b\}$ and $B_1 = Y = A_1$. So in this case the lemma is proved.

If $|M^a| = \ell + 1$ let D_a be the set of nodes in M^a of minimal degree d_{\min} and D_b the analogous set of nodes in M^b . Each node in D_a corresponds to a node in D_b via the isomorphism I.

The value of $F_{G}(p_{a})$ is based by construction on the paths in $\mathcal{V}(p_{a})$. For $v \in D_{a}$ each path $p'_{a} \in \mathcal{P}_{X_{v}^{a}Y_{v}} \cap \mathcal{V}(p_{a})$ corresponds to a path $p'_{b} \in \mathcal{P}_{X_{v}^{b}Y_{u}} \cap \mathcal{V}(p_{b})$, $u := I(v) \in D_{b}$. Is a an edge at v in M^{a} , so b is an edge at u in M^{b} . This leads to $X_{v}^{a} = X_{v}^{b}$ and $Y_{v} = Y_{u}$ and, therefore, $p'_{a} = p'_{b}$. Otherwise, if a is not an edge at v we have v = u. In this case either X^{a} arises from X_{v}^{a} and $Y_{v} = Y$ or $X_{v}^{a} = X^{a}$ and Y arises from Y_{v} by exchanging two edges. The same holds for X_{v}^{b} and Y_{v} . This modification can also be done at X and Y and for the resulting spanning

trees X_v, Y_v and the node w the induction hypothesis holds for all paths in $\mathcal{P}_{X_v^a Y_v}$ and $\mathcal{P}_{X_v^b Y_v}$ that satisfy (3.4). This condition is in particular satisfied by p'_a and p'_b and, therefore, $F_G(p'_a) = F_G(p'_b)$. It follows $F_G(p'_a) = F_G(p'_b)$ for all $p'_a \in \mathcal{V}(p_a)$ and for the corresponding $p'_b \in \mathcal{V}(p_b)$. Finally

$$F_{G}(p_{a}) = \frac{1}{|D_{a}|} \sum_{p_{a}' \in \mathcal{V}(p_{a})} F_{G}(p_{a}') = \frac{1}{|D_{b}|} \sum_{p_{b}' \in \mathcal{V}(p_{b})} F_{G}(p_{b}') = F_{G}(p_{b}).$$

The multicommodity flow F_G yields good upper bounds for the mixing time of $\mathfrak{M}_s(G)$ if no transition of the Markov chain carries too much weight. The following theorem shows that this holds for F_G .

Theorem 3.2 Let B and \overline{B} be two spanning trees of a graph G = (V, E)and let $e \in B \oplus \overline{B}$ be an edge. Define $\mathcal{B} := \mathcal{B}(B, \overline{B}, e)$ as the set of paths $p = (B_i)_{0 \le i \le \ell} \in \mathcal{P}$ such that there exists $j \in \{0, \ldots, \ell - 1\}$ with

- (a) $B = B_i$, i.e., p contains B
- (b) $\bar{B} = B_0 \oplus B_\ell \oplus B$, i.e., the coding of B in p is \bar{B}
- (c) $e \in B_j \oplus B_{j+1}$, i.e., p leaves B by exchanging e

(d)
$$F_{G}(p) > 0$$

Then

$$\sum_{p \in \mathcal{B}} F_G(p) = 1.$$

Proof: We set $M := (V, B \cup B)/(B \cap B)$ and again we proceed inductive over |M|. For |M| = 2 the set $B \oplus \overline{B}$ contains exactly two edges. Thus \mathcal{B} contains only the path $p = (B_i)_{0 \le i \le 1}$ with $B_0 = B$ and $B_1 = \overline{B}$. By definition $F_G(p) = 1$.

Now let $|M| = \ell + 1$ and D be the set of nodes in M of minimal degree d_{\min} . For each $v \in D$ we construct a set $\mathcal{B}_v \subset \mathcal{P}$ with

(i)
$$\sum_{p'\in\mathcal{B}_v}F_G(p')=1,$$

(ii)
$$\sum_{p \in \mathcal{B}} F_G(p) = \sum_{v \in D} \sum_{p' \in \mathcal{B}_v} \frac{1}{|D|} F_G(p').$$

The theorem follows then easily, because

$$\sum_{p \in \mathcal{B}} F_G(p) = \sum_{v \in D} \sum_{p' \in \mathcal{B}_v} \frac{1}{|D|} F_G(p') = \frac{1}{|D|} \cdot \sum_{v \in D} 1 = 1.$$

If $d_{\min} = 2$, let $b \in B$ and let $a \in \overline{B}$ be the two edges at a fixed $v \in D$. If $e \notin \{a, b\}$, we define $B_v := B$ and $\overline{B}_v := (\overline{B} \setminus \{a\}) \cup \{b\}$. The graph $M_v := (V, B_v \cup \overline{B}_v)/(B_v \cap \overline{B}_v)$ has ℓ nodes. Therefore, the properties (a), (b), (c), (d) and also (i) are satisfied by the set $\mathcal{B}_v := \mathcal{B}(B_v, \overline{B}_v, e)$. If $e \in \{a, b\}$, we set $B_v := (B \setminus \{b\}) \cup \{a\}$ and $\overline{B}_v := B_v$. Then $\mathcal{B}_v := \mathcal{P}_{B_v \overline{B}_v}$ satisfies (i) by definition of F_G . To ensure (ii), we show

$$\bigcup_{p \in \mathcal{B}} \mathcal{V}(p) = \bigcup_{w \in D} \mathcal{B}_w.$$
(3.5)

This gives immediately (ii):

$$\sum_{p \in \mathcal{B}} F_G(p) = \sum_{p \in \mathcal{B}} \sum_{p' \in \mathcal{V}(p)} \frac{1}{|D|} F_G(p') = \sum_{v \in D} \sum_{p' \in \mathcal{B}_v} \frac{1}{|D|} F_G(p').$$

While in (3.5) $\bigcup \mathcal{V}(p) \subseteq \bigcup \mathcal{B}_w$ is a consequence of the construction of F_G , $\bigcup \mathcal{V}(p) \supseteq \bigcup \mathcal{B}_w$ one obtains as follows: Take $p \in \mathcal{B}$ and $p' \in \mathcal{V}(p)$, which is based on p via a node $w \in D$. If $e \notin \{a, b\}$, p' is extended to p by adding the exchange of a and b at the first step. By definition of \mathcal{B} , p leaves the spanning tree $B = B_v$ by exchanging e. The same holds, therefore, for p'. But in p' this transition is coded by $\bar{B}' := (\bar{B} \setminus \{a\}) \cup \{b\}$ and so $p' \in \mathcal{B}(B_v, \bar{B}_v, e) = \mathcal{B}_v$. If $e \in \{a, b\}$ we get $p \in \mathcal{P}_{B\bar{B}}$, because a, b are exchanged first in p. Thus the path p' is a path from $B' := (B \setminus \{b\}) \cup \{a\} = B_v$ to $\bar{B} = B_v$ and hence $p' \in \mathcal{B}_v = \mathcal{P}_{B_v\bar{B}_v}$.

The case $d_{\min} = 3$ we treat analogonsly. For $v \in D$ let w.l.o.g. $a, b \in B$ and $c \in \overline{B}$ be the tree edges at v in M. We further define $B_v := B$, $\overline{B}_v^a := (\overline{B} \setminus \{c\}) \cup \{a\}$ and $\overline{B}_v^b := (\overline{B} \setminus \{c\}) \cup \{b\}$. Let $X, Y \in ST(G)$ be the start and end node of a path $p \in \mathcal{B}$ that is based on $p' \in \mathcal{V}(p)$ via a node $w \in D$. We consider at first $e \notin \{a, b, c\}$ and again w.l.o.g. $a, b \in X, c \in Y$. According to the construction of F_G , the edges a, b, and c are exchanged in p in two consecutive transitions. Because $a, b \in B$, both edges are either in X or in Y. The only circle in $X \cup \{c\}$ contains either a or b. If it contains a then $p' \in \mathcal{B}^a := (B_v, \overline{B}_v^a, e)$, else $p' \in \mathcal{B}^b := \mathcal{B}(B_v, \overline{B}_v^b, e)$. For $p' = (B_i)_{0 \le i \le \ell} \in \mathcal{B}^a$, we define $p'' = (A_i)_{0 \le i \le \ell} \in \mathcal{B}^b$ by

$$A_i := \begin{cases} B_i, & 0 \le i \le j\\ B_i \oplus \{a, b\}, & j < i \le \ell \end{cases}$$

with $j \in \{0, \ldots, \ell-1\}$ such that $b \in B_j \oplus B_{j+1}$. These paths p', p'', the spanning trees X, Y and the node w of degree 3 satisfy the prerequisite of Lemma 3.1 and hence $F_G(p') = F_G(p'')$. Furthermore, p'' cannot be in any other $\mathcal{V}(\tilde{p})$. If this would be the case, then $p \in \mathcal{P}_{XY}$ and so $\tilde{p} = p$. For any $p \in \mathcal{B}$, the path $p' \in \mathcal{V}(p)$ according to $w \in D$ is contained either in \mathcal{B}^a or in \mathcal{B}^b , while the corresponding p'' cannot be in another set $\mathcal{V}(\tilde{p})$. Thus $F_G(p') = F_G(p'')$ and by the induction hypothesis

$$\sum_{p'\in\mathcal{B}^a}F_{\scriptscriptstyle G}(p')=\sum_{p'\in\mathcal{B}^b}F_{\scriptscriptstyle G}(p')=1.$$

The set

$$\mathcal{B}_{v} := \{ p' \in \mathcal{B}^{a} \cup \mathcal{B}^{b} \mid \exists \widetilde{p} \in \mathcal{B} : p' \in \mathcal{V}(\widetilde{p}) \},$$
(3.6)

satisfies (i)

$$\sum_{p'\in\mathcal{B}_v}F_{\scriptscriptstyle G}(p')=\sum_{p'\in\mathcal{B}^a}F_{\scriptscriptstyle G}(p')=\sum_{p'\in\mathcal{B}^b}F_{\scriptscriptstyle G}(p')=1.$$

If $e \in \{a, b, c\}$, then we set $\mathcal{B}^a := \mathcal{B}(B_v, \bar{B}^a_v, b)$ and $\mathcal{B}^b := \mathcal{B}(B_v, \bar{B}^b_v, a)$ and proceed as above. We also get in this case a set \mathcal{B}_v with property (i). The definition (3.6) of \mathcal{B}_v ensures that

$$\bigcup_{p\in\mathcal{B}}\mathcal{V}(p)=\bigcup_{v\in D}\mathcal{B}_v.$$

holds, and, therefore, \mathcal{B}_v satisfies (ii). Now the theorem follows as in the case $d_{\min} = 2$.

It is not difficult to see that Theorem 3.2 guarantees (1.11). All preparations are made now to obtain an efficient upper bound on the mixing time of $\mathfrak{M}_s(G)$.

Theorem 3.3 For a graph G = (V, E) the mixing time τ_s of the Markov chain $\mathfrak{M}_s(G)$ is bounded by

$$\tau_s(\varepsilon) \le 2n^2 m \cdot (n \log m + \log \varepsilon^{-1})$$

for all $\varepsilon \in (0, 1)$ with n := |V| and m := |E|.

Proof: In Proposition 2.1 we have seen, that the Markov chain $\mathfrak{M}_s(G)$ meets the prerequisites of the result of Diaconis and Stroock (1991) mentioned in (1.6) and its extension of Sinclair (1992) in (1.12). Hence we already have

$$\tau_s(\varepsilon) \le \varrho(F_G) \cdot (\log \hat{\pi}^{-1} + \log \varepsilon^{-1}) \tag{3.7}$$

with $\hat{\pi} := \min_{x \in \mathrm{ST}(G)} \pi(x)$, and

$$\varrho(F_G) := \max_{\substack{v,w\in\Omega\\P_s(v,w)>0}} \frac{1}{\pi(v) \cdot P_s(v,w)} \cdot \sum_{p_{xy}\in\mathcal{P}(v,w)} \pi(x)\pi(y) \cdot f_{xy}(p_{xy}) \cdot |p_{xy}|,$$

where $\mathcal{P}(v, w)$ as set of paths p, that contain the transition (v, w) and $F_G(p) > 0$. By construction the length of path p with positive weight in F_G is at most in n-1, because two spanning trees differ in at most 2(n-1) edges. Furthermore the stationary distribution of $\mathfrak{M}_s(G)$ is the uniform distribution on $\mathrm{ST}(G)$ and the transition probabilities are either $\frac{1}{2m(n-1)}$ or 0.

This gives

$$\varrho(F_G) \le \frac{2n^2m}{|\operatorname{ST}(G)|} \cdot \max_{\substack{v,w \in \Omega \\ P_s(v,w) > 0}} \sum_{p \in \mathcal{P}(v,w)} F_G(p).$$
(3.8)

We now use Theorem 2.2 to bound the second factor of this estimate: For an arbitrary transition (v, w) of $\mathfrak{M}_s(G)$ and $p = (B_i)_{0 \le i \le 1} \in \mathcal{P}(v, w)$ there is some

 $j \in \{0, \ldots, \ell - 1\}$ with $v = B_j$. Let this v be encoded by \bar{v} . As $v \setminus w$ contains exactly one edge e we obtain $p \in \mathcal{B}(v, \bar{v}, e)$ and hence

$$\mathcal{P}(v,w) \subset \bigcup_{\bar{v}\in \mathrm{ST}(G)} \mathcal{B}(v,\bar{v},e).$$

We deduce with Theorem 2.2

$$\sum_{p \in \mathcal{P}(v,w)} F_G(p) \le \sum_{\bar{v} \in \mathrm{ST}(G)} \sum_{p \in \mathcal{B}(v,\bar{v},e)} F_G(p) = |\Omega|,$$

and with (3.8)

$$\varrho(F_G) \le \frac{2n^2m}{|\operatorname{ST}(G)|} \cdot |\operatorname{ST}(G)| = 2n^2m$$

Together with the rough bound $|\operatorname{ST}(G)| \leq m^n$ in (3.7) we finally get for all $\varepsilon \in (0, 1)$

$$T_s(\varepsilon) \le 2n^2 m \cdot (n\log m + \log \varepsilon^{-1}).$$

4 Canonical paths for \mathfrak{M}_s

For the construction of canonical paths for $\mathfrak{M}_s(G)$ we shall make use of the multicommodity flow F_G in section 3. For $X, Y \in \mathrm{ST}(G)$ for the construction of a 1-flow f_{XY} for any node v of minimal degree in the contracted graph $M = (V, X \cup Y)/(X \cap Y)$ we used by induction a 1-flow $f_{X_vY_v}$ already constructed. If in this recursion this node v is always uniquely determined, then f_{XY} is in fact a 1-flow along some path in $\mathfrak{M}_s(G)$ since the construction begins with a simple transition between neighbours. To obtain canonical paths for $\mathfrak{M}_s(G)$ we have to determine which of the nodes of minimal degree has to be chosen in the recursion step. We call this node in the following the starting node in M.

To construct the starting node in M we assume w.l.g. that M has at least three nodes. If there is exactly one node of minimal degree we call it the starting node. In the other case we numerate the nodes in V by indices $1, \ldots, n$ and consider the subgraph $M' := (V, X \cup Y)$. Each node with minimal degree in M we map injectively to the index of a node in V and choose as starting node of M that of minimal index. A node w in M corresponds to a connected component of $X \cap Y$ and thus to a subtree t_w of M'. A node of t_w is called boundary node if it is an endnode of edges in M' which are not in $X \cap Y$ but in $X \oplus Y$. These edges we call boundary edges. In the tree t_w any pair of nodes is connected by exactly one path in t_w . By s_w we denote the subgraph of M'consisting of the paths which connect boundary node pairs supplemented by boundary edges. A node in t_w is called internal node if its degree in s_w is ≥ 3 .



Figure 4: Boundary nodes in $t_w = 0$, boundary edges = --, internal node o is of degree 3 in s_w .

If w in M has minimal degree $d_{\min} = 3$, then t_w has exactly one internal node whose index we attach to w. This can be seen as follows. If t_w has only one boundary node p, then the boundary edges are the only edges in s_w and so p is the only node from t_w in s_w of degree 3. If there are 2 boundary nodes p and q, then s_w consists of the path between p and q and the three boundary edges. In s_w thus only one boundary node of degree 3 exists with 2 boundary edges. In case t_w has 3 different boundary nodes p, q and r in the first case the path in t_w between two of these nodes might contain the third one. If e.g. r is in the path from p to q, then only r can have degree 3 in s_w induced by the boundary edge at this node. If no boundary node is on the path between the two others, then the final segments of the path from q to p and from r to pcoincide. Let u besides p denote the other end node of this segment, then s_w consists of three disjoint paths to the boundary nodes starting in u and u is the only node from t_w in s_w of degree 3 (see figure 4). Since w is attached this way the index of a node in t_w , this mapping to the index is injective.

If in M the minimal degree $d_{\min} = 2$, then for no node w of degree 2 the corresponding subtree t_w in M' has an inner node since it has at most two boundary nodes. Further, those w are not neighbours to further nodes of degree 2 as M is the union of two disjoint spanning trees. We now attach to both edges at w in M a node in V and then choose as partner of w the smaller of these two indices. The following procedure is demonstrated in Figure 5,6: Let e be an edge in M connecting w with a node v. e is also in M' and connects there a boundary node w' of t_w with a boundary node v' in t_v . If v' is an inner node of t_v then we attach to e the node w'. In the other case we consider the subgraph s_v where v' has degree 2 since it is a boundary node of t_v but it is not an inner node. Therefore, by construction all other boundary nodes are connected by a path in s_v with v' and coincide on the initial segment from v'to some inner point v''. We attach to e not the inner node v'' but its neighbour in this segment. As a result our mapping is injective.



Figure 5: In the middle part we have node w connected via e, f with v and u in M. Boundary nodes = 0, inner nodes = 0.



Figure 6: Corresponding subgraphs s_v and s_u . Determining the index of node w of degree 2. In s_v all paths from v' to boundary nodes coincide on initial edge part up to v''. Neighbour of $v'' = \blacksquare$. Analogously in s_u . The smaller index of the \blacksquare -node is attached to w.

After this involved determination of the starting point we can follow the construction of multicommodity flows in section 3 and construct canonical paths for the Markov chain \mathfrak{M}_s .

Construction of canonical paths in $\mathfrak{M}_{s}(G)$: For $X, Y \in ST(G)$ and M := $(V, X \cup Y)/(X \cap Y)$ let F_G be the multi-commodity flow of $\mathfrak{M}_s(G)$ as in section 3. The canonical path γ_{xy} form X to Y in $\mathfrak{M}_s(G)$ is defined by induction on |M|: If |M| = 2 then X and Y are neighbours and the canonical path is $\gamma_{XY} = (B_i)_{0 \le i \le 1}, B_{\underline{0}} := X, B_{\underline{1}} = Y$. Since $F_G(\gamma_{XY}) = 1$ we choose the corresponding coding $\bar{B}_0 := Y, \bar{B}_1 := X$. For the induction step |M| = l + 1we proceed as in the construction of F_{G} . There however we determined for any node v the set D of G all nodes of minimal degree in $M, X_v, Y_v \in ST(G)$, constructed for any path $p' \in \mathcal{P}_{X_v Y_v}$ with $F_G(p') > 0$ a path $p \in \mathcal{P}_{XY}$ and determined $f_{XY}(p)$ as sum of all $f_{X_vY_v}(p')$ over all $v \in D$ and $p' \in \mathcal{P}_{X_vY_v}$ normed by $\frac{1}{|D|}$. Now by induction hypothesis we have for the starting node v_0 of M and the corresponding $X' := X_{v_0}, Y' := Y_{v_0}$ that there exists already exactly one canonical path $\gamma_{x'y'}$. Like the construction of $p \in \mathcal{P}_{XY}$ from $p' \in \mathcal{P}_{X_v Y_v}$ we obtain a canonical path γ_{xy} from $\gamma_{x'y'}$ and the coding of a transition (B_i, B_{i+1}) in γ_{XY} is given in the same way by $\bar{B}_i := X \oplus Y \oplus B_i$. The set of all canonical paths in $\mathfrak{M}_{s}(G)$ we denote by Γ_{G} .

We next obtain results analogously to Lemma 3.1 and Theorem 3.2. The canonical path γ_{XY} and $\gamma_{X'Y'}$ are similar if the pairs X, Y and X', Y' are close.

Lemma 4.1 Let $X, Y \in ST(G)$ and w a node of degree 3 in M. If $a, b \in Y$

and $c \in X$ are edges to w in M, then $X^a := (X - \{c\}) \cup \{a\}$ and $X^b := (X - \{c\}) \cup \{b\}$ are in ST(G) and for the canonical paths $\gamma_{X^{a_Y}} := (A_i)_{0 \le i \le l}$ and $\gamma_{X^{b_Y}} := (B_i)_{0 \le i \le l}$ holds

$$A_i = \begin{cases} B_i \oplus \{a, b\}, \ 0 \le i \le k\\ B_i, \qquad k < i \le l \end{cases}$$

where k is the place in $\gamma_{x^{a_Y}}$ where the edge b is added, i.e. $b \in A_k \oplus A_{k+1}$. Similarly for $\gamma_{y^{x^a}} := (A'_i)_{0 \le i \le l}, \ \gamma_{y^{x^b}} := (B'_i)_{0 \le i \le l}$ holds

$$A'_{i} = \begin{cases} B'_{i}, & 0 \le i \le k \text{ with } k \in \{0, \dots, l-1\}\\ B_{i} \oplus \{a, b\}, & k < i \le l \end{cases}$$

such that $b \in A'_k \oplus A'_{k+1}$.

The injectivity of the coding is needed to prove that no transitions are used in to many of the canonical paths. This is a consequence of the following theorem which is parallel to Theorem 3.2.

Theorem 4.2 For $B, \overline{B} \in ST(G)$ and edge $e \in B \oplus \overline{B}$ there exists exactly one canonical path $\gamma_{x,y} := (B_i)_{1 \le i \le l}$ and some $j \in \{0, \ldots, l-1\}$ such that

Detailed proofs of Lemma 4.1 and Theorem 4.2 are given in Fehrenbach (2003). As consequence we obtain a proof of the mixing time bound in Theorem 3.3 by canonical paths:

Proof of Theorem 3.3 by canonical paths:

We have for the mixing time $\tau = \tau(\varepsilon)$ by (1.5)

$$\tau(\varepsilon) \le \varrho(\Gamma_G)(\log \hat{\pi} + \log \varepsilon^{-1}) \tag{4.1}$$

where π is the stationary distribution, $\hat{\pi} := \min_{x \in \Omega} \pi(x)$ and

$$\varrho(\Gamma_G) := \max_{\substack{(B,C) \in \Omega^2 \\ \mathcal{P}_s(B,C) > 0}} \frac{1}{\pi(B) \mathcal{P}_s(B,C)} \sum_{\gamma_{XY} \in \mathcal{P}(B,C)} \pi(X) \pi(Y) |\gamma_{XY}|,$$
(4.2)

 $\mathcal{P}(B,C)$ the set of canonical paths which contain the transition (B,C). The maximal length of a canonical path in Γ_G is n-1 since at most 2(n-1) edges are exchanged. Further $P_s(B,C) = \frac{1}{2(n-1)m}$, m = |E|. Thus we get for the congestion measure

$$\varrho(\Gamma_G) \le \frac{2n^2 m}{|\Omega|} \max_{\substack{(B,C) \in \Omega^2 \\ \mathcal{P}_s(B,C) > 0}} |\mathcal{P}(B,C)|.$$

$$(4.3)$$

The max expression can be estimated using Theorem 4.2. For a transistion (B, C) of $\mathfrak{M}_s(G)$ let e be the unique edge in $B \setminus C$. In any canonical path $\gamma_{xy} \in \mathcal{P}(B, C)$ the transition (B, C) is coded by some $\overline{B} \in \Omega$. By Theorem 4.2 there exists exactly one canonical path in Γ_G with these properties. Since this path not necessarily contains (B, C) we conclude that $|\mathcal{P}(B, C)| \leq |\Omega|$. This implies

$$\varrho(\Gamma_G) \le \frac{2n^2 m}{|\Omega|} \cdot |\Omega| = 2n^2 m.$$
(4.4)

With $|\Omega| \leq m^n$ we thus obtain

$$\tau_s(\varepsilon) \le 2n^2 m (n\log m + \log \varepsilon^{-1}). \tag{4.5}$$

5 Forests with roots

In this section we apply the multi-commodity flows resp. canonical paths to the analysis of the mixing time of some Markov chains on forests. The Markov chain \mathfrak{M}_s introduced in sections 2, 3 on the set of spanning trees only uses exchanges of two edges. These transitions can also be used on the class of forests i.e. circle free subgraphs of G and the corresponding Markov chain has an stationary distribution the uniform distribution. But sofar no efficient bounds for the mixing time of this or related Markov chains are known and also no randomized approximation schemes for the number of forests are known (see Welsh and Merino (2000)). It seems that also the canonical paths of section 4 transfered to this problem do not lead to a polynomial bound for the mixing time. In the following we consider the modified class of forests with roots $F_r(G)$ and show that for this modified space $\Omega = F_r(G)$ we obtain rapid mixing results for various Markov chains by means of the corresponding canonical paths constructed for the class of spanning trees.

Definition 5.1 (Forests with roots) Let G = (V, E) be an undirected graph. A pair $X := (R_X, E_X)$ with $R_X \subset V, E_X \subset E$ is called forest with roots if

- the subgraph (V, E_X) of G contains no circle
- any connected component Z of (V, E_x) has exactly one node in R_x , which we call the root of Z.

 $F_r(G)$ denotes the set of all forests with roots.

Counting forests with roots corresponds to counting forests X with connected components Z_1, \ldots, Z_d which are weighted by the number of possibilities to choose a root system i.e. by $\prod_{i=1}^d |Z_i|(n-|X|)$. The class $F_r(G)$ of forests with roots can be identified with the class of spanning trees of an extended graph G'.

Lemma 5.2 For any undirected graph G = (V, E) there exists a graph G' = (V', E'), such that there exists a bijection $Sp : F_r(G)) \longrightarrow ST(G')$.

Proof: Let $V' := V \cup \{r\}$ and $E' := E \cup \{\{r, v\} \mid v \in V\}$ i.e. we add a node rand all edges $\{r, v\}$ to the new node to obtain G' = (V', E'). For $X \in F_r(G)$ we define $Sp(X) := E_X \cup \{\{r, v\} \mid v \in R_X\}$. Thus Sp(X) is a spanning tree of G'since E_X is circlefree and also the addition of the edges $\{r, v\}, v \in R_X$, does not produce circles. Sp is a bijection since any $X' \in ST(G')$ has a unique origin $Sp^{-1}(X') = (R_X, E_X)$ where $R_X := \{v \in V \mid \{r, v\} \in X'\}$ and $E_X := X' \cap E$. \Box

The bijection of Lemma 5.2 implies that $M_s(G')$ induces a rapidly mixing Markov chain on $F_r(G)$. We now introduce a more general class of Markov chains on $F_r(G)$ and investigate their mixing behaviour. We allow that the transition behaviour of the Markov chains depends on the degree $d_X(r) =:$ $||X||, X \in ST(G')$, of the newly added node r i.e. it depends on the number of connected components of the forest corresponding to $X \in SB(G')$.

Definition 5.3 Let G = (V, E) be an undirected graph with extension G' = (V', E') as in Lemma 5.2. For any $\lambda \in \mathbb{R}_+$ we define the Markov chain $\mathfrak{M}_s^{\lambda}(G') = (X_t)_{t \in \mathbb{N}}$ on ST(G') by the transition probabilities: If $X_t = X \in ST(G')$ is the state of $\mathfrak{M}_s(G')$ at the time $t \in \mathbb{N}$, then we draw uniformly and independent $e \in X$ und $f \in E'$ and set

- 1. $Y := (X \setminus \{e\}) \cup \{f\}$
- 2. If $Y \in ST(G')$, then we set

 $X_{t+1} = \begin{cases} Y, & with \ probability \ p \\ X, & with \ probability \ 1-p, \end{cases}$

where
$$p := \frac{1}{2} \min \left\{ 1, \lambda^{\|Y\| - \|X\|} \right\}.$$

If $Y \notin ST(G')$, then we set $X_{t+1} := X$. We denote the transition matrix of this chain by P_{λ} .

In the Markov chain $\mathfrak{M}_s^{\lambda}(G')$ for $0 < \lambda < 1$ transitions to forests with smaller number of components are preferred, for $1 < \lambda$ transitions to forests with bigger number of components are preferred while for $\lambda = 1$ we have the chain of section 2 on $G', \mathfrak{M}_s^{\lambda}(G') = \mathfrak{M}_s(G')$. The consequence for the stationary distribution is the following.

Theorem 5.4 For any $\lambda \in \mathbb{R}^+$ the Markov chain $\mathfrak{M}^{\lambda}_{s}(G')$ is ergodic. The stationary distribution π_{λ} is given by

$$\pi_{\lambda}(X) := \frac{\lambda^{\|X\|}}{Z(\lambda)} \tag{5.1}$$

with normalization $Z(\lambda) := \sum_{X \in ST(G')} \lambda^{||X||}$.

Proof: $\mathfrak{M}_s^{\lambda}(G')$ has the same transition graph as $\mathfrak{M}_s(G')$ and thus is irreducible and aperiodic by step 2 in the definition of $\mathfrak{M}_s^{\lambda}(G')$. Further for $X, Y \in ST(G')$ with $P_{\lambda}(X,Y) > 0$ holds:

$$\begin{split} \pi_{\lambda}(X) \ P_{\lambda}(X,Y) &= \frac{1}{2m(n-1)} \ \frac{\lambda^{\parallel^{X\parallel}}}{Z(\lambda)} \ \min\left\{1,\lambda^{\parallel^{Y\parallel}-\parallel^{X\parallel}}\right\} \\ &= \frac{1}{2m(n-1)} \ \frac{1}{Z(\lambda)} \ \min\left\{\lambda^{\parallel^{X\parallel}},\lambda^{\parallel^{Y\parallel}}\right\} \\ &= \frac{1}{2m(n-1)} \ \frac{\lambda^{\parallel^{Y\parallel}}}{Z(\lambda)} \ \min\left\{\lambda^{\parallel^{X\parallel}-\parallel^{Y\parallel}},1\right\} \\ &= \pi_{\lambda}(Y) \ P_{\lambda}(Y,X), \end{split}$$

with n := |V'|, m := |E'|. Thus π_{λ} is the stationary distribution of $\mathfrak{M}_s^{\lambda}(G')$. \Box

In the next theorem we use the canonical paths of section 4 to estimate the mixing time of $\mathfrak{M}_s^{\lambda}(G')$ efficiently. In consequence we have a polynomial sampling scheme for the set of forests of any graph G with weights proportional to $\lambda^{d(X)}, d(X)$ the number of connected components of X.

Theorem 5.5 Let G' = (V', E') be the extension of an undirected graph G = (V, E) and $\lambda \in \mathbb{R}^+$. Then the mixing time τ_{λ} of the Markov chain $\mathfrak{M}_s^{\lambda}(G')$ is bounded by

$$\tau_{\lambda}(\varepsilon) \le 2n^2 m \cdot \lambda' \cdot (n \log(m\lambda') + \log \varepsilon^{-1}), \tag{5.2}$$

for all $\varepsilon \in (0,1)$, where $\lambda' := \max\{\lambda, \lambda^{-1}\}$, n := |V'| and m := |E'|.

Proof: The Markov chains $\mathfrak{M}_s^{\lambda}(G')$ and $\mathfrak{M}_s(G')$ have the same transition graph. Therefore we can use the canonical paths $\Gamma_{G'}$ w.r.t. $\mathfrak{M}_s(G')$ of section 4. We have to estimate the congestion measure

$$\varrho_{\lambda}(\Gamma_{G'}) := \max_{\substack{(B,C)\in SB(G')^2\\P_{\lambda}(B,C)>0}} \frac{1}{\pi_{\lambda}(B) P_{\lambda}(B,C)} \sum_{\gamma_{XY}\in\mathcal{P}(B,C)} \pi_{\lambda}(X)\pi_{\lambda}(Y) |\gamma_{XY}|, \quad (5.3)$$

where $\mathcal{P}(B, C)$ is the set of canonical paths in $\Gamma_{G'}$ which use transition (B, C). The length of each canonical path is bounded by n-1 and for $B \neq C$ holds $\mathcal{P}_{\lambda}(B, C) \geq \frac{1}{2m(n-1)\lambda'}$. Thus from (5.3)

$$\varrho_{\lambda}(\Gamma_{G'}) \leq \frac{2n^2m \ \lambda'}{Z(\lambda)} \max_{P_{\lambda}(B,C)>0} \sum_{\gamma_{XY} \in \mathcal{P}(B,C)} \frac{\lambda^{\|X\|+\|Y\|}}{\lambda^{\|B\|}}.$$

For any fixed transition (B, C) of $\mathfrak{M}_s^{\lambda}(G')$ and $\gamma_{XY} \in \mathcal{P}(B, C)$, this transition is coded by $\overline{B} = X \oplus Y \oplus B$. As $B \setminus C$ contains exactly one edge, say $e \in E'$, there is by Theorem 4.2 at most one canonical path which codes B by \overline{B} and leads from B directly to C. Further, by construction of the paths and their codings it holds that $B \oplus \overline{B} = X \oplus Y$ as well as $B \cap \overline{B} = X \cap Y$. This implies that $||B|| + ||\bar{B}|| = ||X|| + ||Y||$ and we obtain for all transitions (B, C) of $\mathfrak{M}_s^{\lambda}(G')$

$$\sum_{\substack{\gamma_{XY} \in \mathcal{P}(B,C) \\ \lambda^{\|S\|} \\ \lambda^{\|B\|}}} \leq \sum_{\bar{B} \in ST(G')} \lambda^{\|\bar{B}\|} = Z(\lambda).$$

As a result,

$$\varrho_{\lambda}(\Gamma_{G'}) \le 2n^2 m \lambda' \tag{5.4}$$

and with $\hat{\pi}_{\scriptscriptstyle{\lambda}} := \min_{\scriptscriptstyle{X} \in SB(G')} \pi_{\scriptscriptstyle{\lambda}}(X)$

$$\tau_{\lambda}(\varepsilon) \le 2n^2 m \,\lambda' \,(\log \hat{\pi}_{\lambda}^{-1} + \log \varepsilon^{-1}). \tag{5.5}$$

For $\lambda < 1$ holds $\hat{\pi}_{\lambda}^{-1} \leq \lambda^{-n} Z(\lambda) \leq (\lambda')^n |ST(G')|$ and for $\lambda \geq 1$, $\hat{\pi}_{\lambda}^{-1} \leq Z(\lambda) \leq (\lambda')^n |ST(G')|$. With $|ST(G')| \leq m^n$ this implies

$$\tau_{\lambda}(\varepsilon) \leq 2n^2 m \cdot \lambda' \ (n \log(m\lambda') + \log \varepsilon^{-1}).$$

Remark: For the transition from $\mathfrak{M}_s^{\lambda}(G')$ via the bijection Sp from Lemma 5.2 to the corresponding Markov chain on $F_r(G)$ we have to note that |V| = |V'| - 1 and |E| = |E'| - |V| which changes the bound only by a polynomical factor. As a consequence we obtain a rapidly mixing Markov chain on the class of forests with roots $F_r(G)$ or equivalently on the class of spanning trees in a rooted graph G' with stationary distribution proportional to $\lambda^{d(X)}$, d(X) the degree of the root r.

6 Connected, spanning subgraphs

In this section we consider the class of connected, spanning subgraphs $S_c(G)$ of a graph G = (V, E). As any $X \in S_c(G)$ has node set V we can identify X with its node set and identify thus $X \subset E$ with subsets of E which define connected spanning subgraphs.

Also for $S_c(G)$ no efficient randomized approximation scheme and no rapidly mixing Markov chain with uniform distribution on $S_c(G)$ as stationary distribution is known (see Welsh and Merino (2000)). We have the following connection of $S_c(G)$ to spanning trees.

Lemma 6.1 For an undirected graph G = (V, E) there exists a graph G'' := (V'', E'') such that there exists a bijection between ST(G'') and

$$\bigcup_{A \in S_c(G)} \left\{ (A, T) \mid T \in ST(A) \right\}$$

Proof: Let $V_E := \{v_e \mid e \in E\}$ be a set of new nodes and define G'' := (V'', E'') with $V'' := V \cup V_E, E'' := \bigcup_{e \in E} \{\{v, v_e\} \mid v \in e\}$, i.e. the edge $e = \{v, w\}$ is replaced by two edges $\{v, v_e\}$ and $\{w, v_e\}$. For each node $e \in E$ we denote one endnode by e_r as right endnode and one endnode by e_l as left endnode. For $X \in ST(G'')$ the subset $A := \{e \in E \mid \{v_e, e_r\} \in X\}$ is a connected spanning subgraph of G. Further, $T := \{e \in E \mid \{v_e, e_r\} \in X \text{ and } \{v_e, e_l\} \in X\}$ is a spanning tree of G.

Conversely X can be reconstructed from A and T since

$$X = \{\{v_e, e_r\} \mid e \in A\} \cup \{\{v_e, e_l\} \mid e \in T \cup (E \setminus A)\}.$$

Thus this mapping is bijective.

Thus any $A \in S_c(G)$ corresponds to as many spanning trees of G'' as A has itself. We introduce as in section 5 a weighting on ST(G'') by

$$\|X\| \coloneqq |A| \tag{6.1}$$

where $X \in ST(G'')$ corresponds to (A, T) in Lemma 6.1.

Definition 6.2 (Markov chain on ST(G'')) We define for $\lambda \in \mathbb{R}^+$ the Markov chain $\mathfrak{M}_{S_c}^{\lambda}(G'') = (X_t)$ on ST(G'') as in Definition 5.3 where the norm ||X|| is defined by (6.1).

Similarly to the argument in section 5 we obtain (for details of the argument see Fehrenbach (2003))

Theorem 6.3 The Markov chain $\mathfrak{M}_{S_c^{\lambda}}(G'')$ is ergodic for any $\lambda \in \mathbb{R}^+$ with stationary distribution

$$\pi_{\lambda}(X) := \frac{\lambda^{\|X\|}}{Z(\lambda)} \quad with \quad Z(\lambda) := \sum_{X \in ST(G')} \lambda^{\|X\|}$$
(6.2)

for $X \in ST(G'')$. The mixing time τ_{λ} is bounded by

$$\tau_{\lambda}(\varepsilon) \le 2n^2 m \lambda' (n \log(m\lambda') + \log \varepsilon^{-1}), \tag{6.3}$$

for all $\varepsilon \in (0,1)$ with $\lambda' := \max\{\lambda, \lambda^{-1}\}$, n := |V''| and m := |E''|.

Based on Lemma 6.1 we can transfer the Markov chain $\mathfrak{M}_{S_c}^{\lambda}(G'')$ on the basic space $\bigcup_{A \in S_c(G)} \{(A, T); T \in ST(A)\}$ and project it on $S_c(G)$. Then we obtain a Markov chain $\mathfrak{M}_{S_c}^{\lambda}(G)$ on $S_c(G)$. The weight of a state $A \in S_c(G)$ w.r.t. its stationary distribution is given by $\lambda^{|A|} |ST(A)|$. The rapid mixing property remains the same since the number of edges and nodes of G and G'' only differ by a polynomial factor. Thus we obtain

Corollary 6.4 The Markov chain $\mathfrak{M}_{S_c}^{\lambda}(G)$ induced by $\mathfrak{M}_{S_c}^{\lambda}(G'')$ on $S_c(G)$ is rapidly mixing with stationary distribution

$$\pi_{\lambda}(A) = \lambda^{|A|} |ST(A)|, \quad A \in S_c(G).$$
(6.4)

Remark: As consequence of Corollary 6.4 we do not get a polynomial randomized approximation scheme for $|S_c(G)|$ as π_{λ} is not the uniform distribution. We may however obtain such a scheme for some functionals like $\sum_{A \in S_c(G)} |ST(A)|$. This however can also directly be obtained from |ST(G)| since

$$\sum_{A \in S_c(G)} |ST(A)| = 2^{m - (n-1)} |ST(G)|$$

since |E - T| = m - (n - 1) for all $T \in ST(G)$.

References

- Aldous, D. (1983). Random walks on finite groups and rapidly mixing Markov chains, Volume 986 of Lecture Notes in Mathematics, pp. 243–297. Springer.
- Aldous, D. (1990). The random walk construction of uniform spanning trees and uniform labelled trees. SIAM Journal on Discrete Mathematics 3, 450– 465.
- Broder, A. (1989). Generating random spanning trees. In *Proceedings of* the 30th Annual IEEE Symposium on Foundations of Computer Science (FOCS), pp. 442–447.
- Cordovil, R. and M. Moreira (1993). Bases-cobases graphs and polytopes of matroids. *Combinatorica* 13, 157–165.
- Cryan, M., M. Dyer, L. A. Goldberg, and M. Jerrum (2002). Rapidly mixing Markov chains for sampling contingency tables with a constant number of rows. In *Proceedings of the 43rd Symposium on Foundations of Computer Science (FOCS)*, pp. 711–720.
- Diaconis, P. (1988). Group Representations in Probability and Statistics. Number 11 in IMS Lecture Notes, Monograph Series. Hayward.
- Diaconis, P. and D. Stroock (1991). Geometric bounds for eigenvalues of Markov chains. Ann. Appl. Prob. 1, 36–61.
- Diestel, R. (1996). Graphentheorie. Springer.
- Feder, T. and M. Mihail (1992). Balanced matroids. In *Proceedings of the 24th* Annual ACM Symposium on Theory of Computing, pp. 26–38.
- Fehrenbach, J. (2003). Design und Analyse stochastischer Algorithmen auf kombinatorischen Strukturen. PhD thesis, University of Freiburg.
- Jerrum, M. (1998). Mathematical foundations of the Markov chain Monte Carlo method. In M. Habib et al. (Eds.), *Probabilistic Methods for Algorithmic Discrete Mathematics*, Number 16 in Algorithms Comb., pp. 116–165. Springer.
- Jerrum, M. (2003). Counting, Sampling and Integrating: Algorithms and Complexity. Lectures in Mathematics. Birkhäuser.

- Jerrum, M. and A. Sinclair (1996). The Markov chain Monte Carlo method: an approach to approximate counting and integration. In D. Hochbaum (Ed.), Approximation Algorithms for NP-hard problems, pp. 482–520. PWS Publishing.
- Jerrum, M. and J.-B. Son (2002). Spectral gap and log-Sobolev constant for balanced matroids. In 43rd IEEE Symposium on Foundations of Computer Science, pp. 721–729. Computer Society Press.
- Jerrum, M., L. G. Valiant, and V. V. Vazirani (1986). Random generation of combinatorial structures from a uniform distribution. *Theor. Comput.* Sci. 43, 169–188.
- Morris, B. and A. Sinclair (2004). Random walks on truncated cubes and sampling 0 1 knapsack solutions. *SIAM, Journal on Computing* 34, 195–226.
- Sinclair, A. (1992). Improved bounds for mixing rates of Markov chains and multicommodity flow. Comb. Probab. Comput. 1, 351–370.
- Sinclair, A. (1993). Algorithms for Random Generation and Counting: a Markov Chain Approach. Progress in Theoretical Computer Science. Birkhäuser. viii +146 p.
- Welsh, D. and C. Merino (2000). The Potts model and the Tutte polynomial. Math. Physics 41, 1127–1152.

Johannes Fehrenbach Department of Mathematics University of Freiburg Eckerstr. 1 79104 Freiburg Germany Ludger Rüschendorf Department of Mathematics University of Freiburg Eckerstr. 1 79104 Freiburg Germany